

GX GEARBOXES

Characterised by a low backlash, GX gearboxes are ideal for applications needing high torque and optimum motion quality.

In combination with NX servo motors, they offer a compact geared servo motor solution optimised to provide the best dynamic performances.



GX gearboxes - NX servo motors Mechanical associations

Motor Torque ; Inertia	GX gearbox size						
	01	02	04	06	07	09	10
NX110 0.45 ; 1.3	GX1...R01 r = 3 to 35	GX1...R02 r = 40 to 80					
NX210 1 ; 3.8	GX2...R01 r = 3 to 15	GX2...R02 r = 20 to 35	GX2...R04 r = 40 to 80				
NX310 2 ; 7.9	GX3...R01 r = 3 to 8	GX3...R02 r = 9 to 20	GX3...R04 r = 25 to 60				
NX420 4 ; 29			GX4...R04 r = 3 to 10	GX4...R06 r = 15 to 60	GX4...R07 r = 70 to 90		
NX430 5.5 ; 42.6			GX4...R04 r = 3 to 10	GX4...R06 r = 15 to 35	GX4...R07 r = 40 to 70		
NX620 8 ; 98				GX6...R06 r = 3 to 10	GX6...R07 r = 15 to 60		
NX630 12 ; 147				GX6...R06 r = 3 to 10	GX6...R07 r = 15 to 50		
NX820 16 ; 320				GX8...R06 r = 3 to 10	GX8...R07 r = 15 to 30	GX8...R09 r = 35 to 50	GX8...R10 r = 60 to 80
NX840 28 ; 620				GX8...R06 r = 3 to 9	GX8...R07 r = 10 to 15	GX8...R09 r = 20 to 30	GX8...R10 r = 35 to 50
NX860 41 ; 920				GX8...R06 r = 3 to 7	GX8...R07 r = 8 to 10	GX8...R09 r = 15 to 20	GX8...R10 r = 25 and 35
NX860V 64 ; 920				GX8...R06 r = 3 to 5	GX8...R07 r = 6 and 8	GX8...R09 r = 9 to 15	GX8...R10 r = 20 to 25

r = gearbox ratio, torque (N.m) and Inertia (10^{-5} .kgm²)

Geared servo motor selection example

Targeted output speed (Ns) : 115 rpm
 Targeted output torque (Cs) : 445 N.m
 Load inertia (Jch) : 3 kgm²

Calculation of the gearbox ratio r

Motor maximum speed (NmaxM) : 4000 rpm
 $r = N_{maxM} / N_s$
 => $4000 / 115 = 34,78$

By choosing the existing ratio immediately above : R=35

Calculation of the motor torque

Torque at low speed = $C_s / r / 0.85^*$
 => $445 / 35 / 0.85 = 14.9$ N.m

Geared servo motor selection

Motor: NX820 (Torque : 16 N.m, Inertia (Jmot) : 320 kgm².10⁻⁵)
 Gearbox : GX8N035R0900 (size 9 ; speed ratio 35)

Calculation of the inertia ratio**

Inertia ratio = $J_{ch} / (J_{mot} \times r^2)$
 => $3 / (320.10^{-5} \times 35^2) = 0.77$

IMPORTANT : please confirm the operating limit of the association selected above with our technical service centre.

HIGH PERFORMANCE GEARED SERVO MOTORS

LARGE CHOICE OF SPEED RATIO

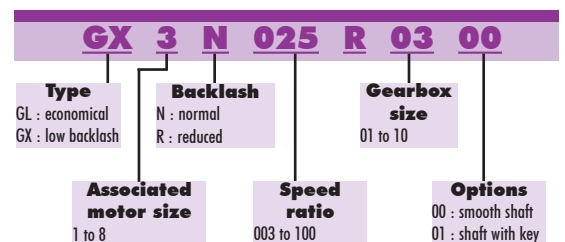
LOW BACKLASH, SMOOTH AND QUIET FUNCTIONING

HIGH STIFFNESS

LIFE LUBRICATED

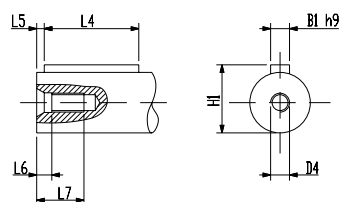
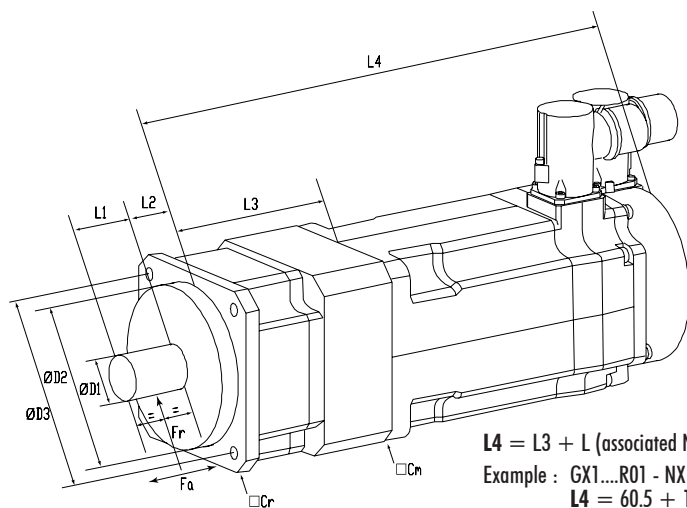
TOP QUALITY FINISHING

UP TO IP65 PROTECTION



Example : GX3N025R0300

GX gearbox, size 3, ratio 25, normal backlash, smooth shaft, NX310 associated motor



Shaft with key option

$L4 = L3 + L$ (associated NX length, drawing on page 15)

Example : GX1....R01 - NX1 motor : L = 133 mm

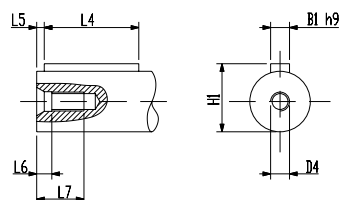
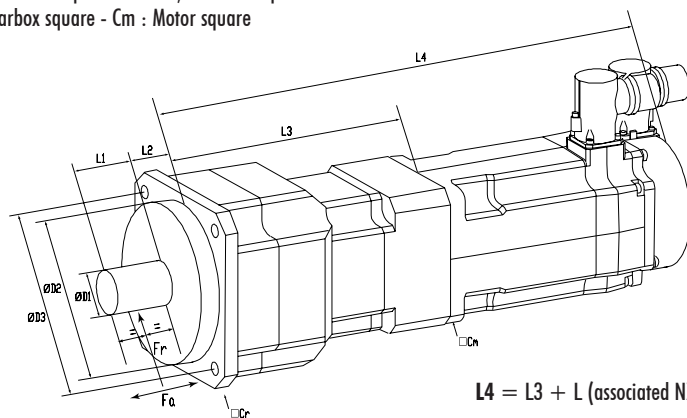
$L4 = 60.5 + 133 = 193.5$ mm

Geared servo motors characteristics and dimensions - 1 stage GX Ratio 3, 4, 5, 6, 7, 8, 9 and 10

Type	Backlash* (min)	Stiffness (N.m/rad)	Fr** (daN)	Fa** (daN)	L1 (mm)	L2 (mm)	L3 (mm)	D1 (mm)	D2 (mm)	D3 (mm)	Cr (mm)	Cm (mm)	L4 (mm)	L5 (mm)	B1 (mm)	H1 (mm)	L6 (mm)	L7 (mm)	D4 (mm)
GX1....R01	5	10000	78	39	20.5	5.5	60.5	13j6	35g6	46	42	42	16	2	5	15	3.2	10	M4x0.7
GX2....R01	5	10000	78	39	20.5	5.5	60.5	13j6	35g6	46	42	56	16	2	5	15	3.2	10	M4x0.7
GX3....R01	5	10000	78	39	20.5	5.5	60.5	13j6	35g6	46	42	71	16	2	5	15	3.2	10	M4x0.7
GX3....R02	5 or 3	24000	153	76	30	7	76.5	16j6	50g6	70	60	71	25	2	5	18	4	12.5	M5x0.8
GX4....R04	5 or 3	48000	325	162	38	10	96	22j6	80g6	100	90	91.5	32	3	6	24.5	6	19	M8x1.25
GX4....R06	5 or 3	80000	670	335	53	12	122	32j6	110g6	130	115	91.5	40	5	10	35	9.5	28	M12x1.75
GX6....R06	5 or 3	80000	670	335	53	12	122	32j6	110g6	130	115	121	40	5	10	35	9.5	28	M12x1.75
GX8....R06	5 or 3	80000	670	335	53	12	122	32j6	110g6	130	115	155	40	5	10	35	9.5	28	M12x1.75
GX8....R07	5 or 3	170000	940	470	82	15	142.5	40j6	130g6	165	142	155	63	5	12	43	12	36	M16x2
GX8....R09	5 or 3	500000	1450	725	85	20	180.5	55j6	160g6	215	180	155	70	6	16	59	15	42	M20x2.5

* Low backlash option : 3 min; ** at 100 rpm

Cr : Gearbox square - Cm : Motor square



Shaft with key option

$L4 = L3 + L$ (associated NX length, drawing on page 15)

Geared servo motors characteristics and dimensions - 2 stages GX Ratio 15, 20, 25, 30, 35, 40, 45, 50, 60, 70, 80, 90 and 100

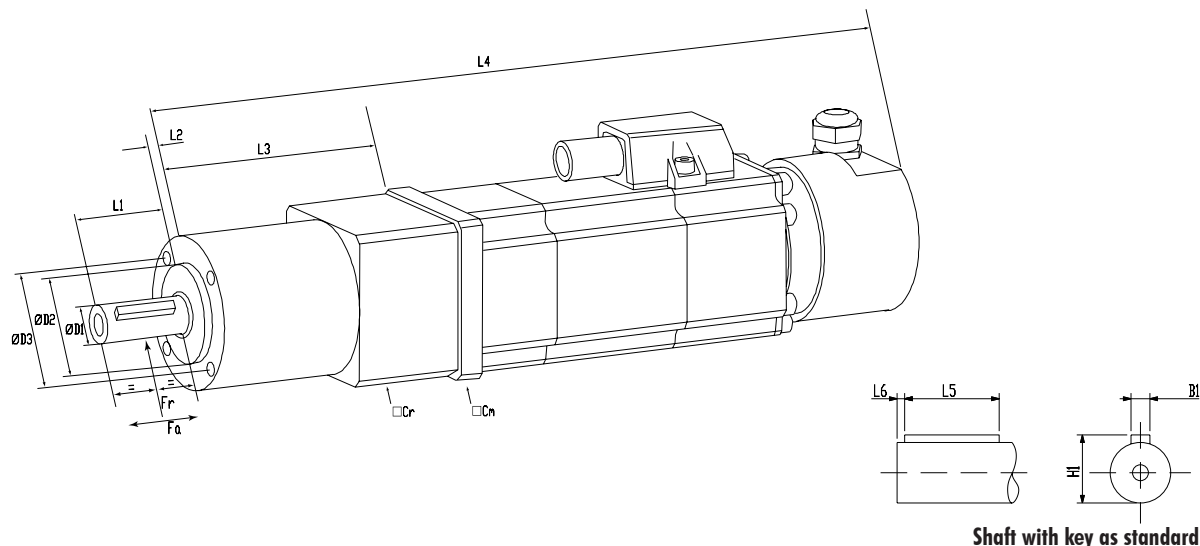
Type	Backlash* (min)	Stiffness (N.m/rad)	Fr** (daN)	Fa** (daN)	L1 (mm)	L2 (mm)	L3 (mm)	D1 (mm)	D2 (mm)	D3 (mm)	Cr (mm)	Cm (mm)	L4 (mm)	L5 (mm)	B1 (mm)	H1 (mm)	L6 (mm)	L7 (mm)	D4 (mm)
GX1....R01	8	10000	78	39	20.5	5.5	88	13j6	35g6	46	42	42	16	2	5	15	3.2	10	M4x0.7
GX1....R02	8 or 6	24000	153	76	30	7	101.5	16j6	50g6	70	60	42	25	2	5	18	4	12.5	M5x0.8
GX2....R01	8	10000	78	39	20.5	5.5	88	13j6	35g6	46	42	56	16	2	5	15	3.2	10	M4x0.7
GX2....R02	8 or 6	24000	153	76	30	7	101.5	16j6	50g6	70	60	56	25	2	5	18	4	12.5	M5x0.8
GX2....R04	8 or 6	48000	325	162	38	10	127	22j6	80g6	100	90	56	32	3	6	24.5	6	19	M8x1.25
GX3....R02	8 or 6	24000	153	76	30	7	101.5	16j6	50g6	70	60	71	25	2	5	18	4	12.5	M5x0.8
GX3....R04	8 or 6	48000	325	162	38	10	127	22j6	80g6	100	90	71	32	3	6	24.5	6	19	M8x1.25
GX4....R06	8 or 6	80000	670	335	53	12	161	32j6	110g6	130	115	91.5	40	5	10	35	9.5	28	M12x1.75
GX4....R07	8 or 6	170000	940	470	82	15	196	40j6	130g6	165	142	91.5	63	5	12	43	12	36	M16x2
GX6....R07	8 or 6	170000	940	470	82	15	196	40j6	130g6	165	142	121	63	5	12	43	12	36	M16x2
GX8....R07	8 or 6	170000	940	470	82	15	196	40j6	130g6	165	142	155	63	5	12	43	12	36	M16x2
GX8....R09	8 or 6	500000	1450	725	85	20	232.5	55j6	160g6	215	180	155	70	6	16	59	15	42	M20x2.5
GX8....R10	8 or 6	770000	5000	2500	108	30	274.5	75j6	180g6	235	220	155	90	7	20	79.5	15	42	M20x2.5

* Low backlash option : 6 min; ** at 100 rpm - Cr : Gearbox square - Cm : Motor square

GL GEARBOXES

GL gearboxes are an economical alternative perfectly adapted to usual applications where a low backlash is not requested.

They are associated to NX servo motors of size 1 to 3.



Shaft with key as standard

Geared servo motors characteristics and dimensions - 1 stage GL Ratio 5 and 8

Type	Backlash (min)	Stiffness (N.m/rad)	Fr* (daN)	Fa* (daN)	L1 (mm)	L2 (mm)	L3 (mm)	D1 (mm)	D2 (mm)	D3 (mm)	Cr (mm)	Cm (mm)	L4 no brake (mm)	L4 with brake (mm)	L5 (mm)	L6 (mm)	B1 (mm)	H1 (mm)
GL1...R01	30	1500	20	20	23	2	67.5	10h7	26h7	34	40	42	200.5	231.5	18	2.5	3	11.2
GL2...R02	20	5000	50	60	30	3	71.5	14h7	40h7	52	60	56	208.5	250.5	25	2.5	5	16
GL3...R02	20	5000	50	60	30	3	71.5	14h7	40h7	52	70	71	217.5	265.5	25	2.5	5	16

Geared servo motors characteristics and dimensions - 2 stages GL Ratio 9, 12, 15, 16, 20, and 25

Type	Backlash (min)	Stiffness (N.m/rad)	Fr* (daN)	Fa* (daN)	L1 (mm)	L2 (mm)	L3 (mm)	D1 (mm)	D2 (mm)	D3 (mm)	Cr (mm)	Cm (mm)	L4 no brake (mm)	L4 with brake (mm)	L5 (mm)	L6 (mm)	B1 (mm)	H1 (mm)
GL1...R01	35	1600	20	20	23	2	80.5	10h7	26h7	34	40	42	213.5	244.5	18	2.5	3	11.2
GL2...R02	25	5000	50	60	30	3	83.5	14h7	40h7	52	60	56	220.5	262.5	25	2.5	5	16
GL3...R02	25	5000	50	60	30	3	83.5	14h7	40h7	52	70	71	229.5	277.5	25	2.5	5	16

* at 100 rpm - Cr : Gearbox square - Cm : Motor square

ECONOMICAL GEARED SERVO MOTORS

HIGH COMPACTY

ROBUST DESIGN

LIFE LUBRICATED

UP TO IP54 PROTECTION

Mechanical associations GL gearboxes - NX servo motors

Motor Torque ; Inertia	GL gearbox size	
	01	02
NX110 0.45 ; 1.3	GL1...R01 r = 5 to 64	
NX210 1 ; 3.8		GL2...R02 r = 5 to 64
NX310 2 ; 7.9		GL3...R02 r = 5 to 64

r = speed ratio, Torque (N.m) and Inertia (10⁻⁵.kgm²)

IMPORTANT : please confirm the operating limit of the association selected above with our technical service centre.